

Program of the day

- Overview of course, exercises, P2
- Introduction to Integer Programming
- Modelling (Williams, chapter 9)
- Applications: Opencast mining
- Ladies or tigers

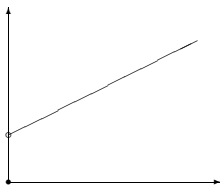
Purpose of the course

- To learn to build complex models from real life using Mathematical Programming
- To know techniques for solving Mathematical Programming models
- To understand that some problems can be solved efficiently and some cannot
- To learn that the same problem may be formulated in different ways, which are easier/harder to solve
- To know a number of techniques for decreasing solution times (or turn a problem from practically “unsolvable” to “solvable”)

Integer Programming

In first part of course: continuous variables, linear constraints

- Most products are integral (apart from liquids)
Airplane production, Tomato Soups
- Structure of problem leads to IP
Graph problems
- Nonlinear objective functions or constraints occur frequently



- Logical conditions
“If I use vegetable oil in the blend, then I must also add 5ml of preservatives”

Integer Programming

General formulation:

$$\begin{aligned}
 &\text{maximize} && \sum_{j=1}^n c_j x_j \\
 &\text{subject to} && \sum_{j=1}^n a_{1j} x_j \leq b_1 \\
 &&& \vdots \\
 &&& \sum_{j=1}^n a_{mj} x_j \leq b_m \\
 &&& x_j \geq 0, \quad j = 1, \dots, n, \quad x \text{ integer}
 \end{aligned}$$

where

- A is a $m \times n$ matrix
- b is a m -vector
- c is a n -vector
- IP: integer programming model
- ILP: integer *linear* model (all constraints linear)
- PIP: pure integer programming model
- MIP: mixed integer programming model

Integer Programming, why?

- IP is much more expressible than LP
- As IP is NP-hard, all NP-hard problems can be formulated as IP-models

But

- IP is not an ideal model
- Many problems cannot be formulated as IP-models in a simple way
- All NP-complete problems are “equivalent” and hence equally good
- IP proposed by Edmonds: Expressibility and LP-bounds

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Integer Programming

IP powerful method for modelling

- LP easy to solve by e.g. Simplex (polynomial time by interior-point methods).
- General IP is NP-hard
- Many concrete problems may be solved despite NP-hardness
- Specific techniques for individual problems

Special problems

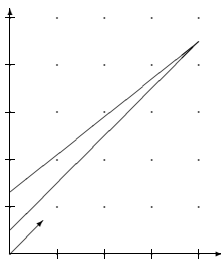
- travelling salesman problem
- project selection
- transportation problem
- assignment problem
- assembly line balancing
- set partitioning problem
- aircrew scheduling
- depot location problem
- sequencing problem
- job-shop scheduling

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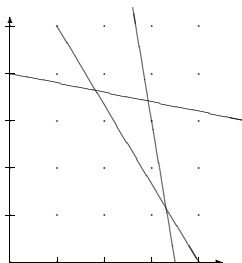
Hardness of IP

$$\begin{aligned} &\text{maximize } x_1 + x_2 \\ &\text{subject to } -2x_1 + 2x_2 \geq 1 \\ &\quad \quad -8x_1 + 10x_2 \leq 13 \\ &\quad \quad x_1, x_2 \geq 0, \text{ integer} \end{aligned}$$

Solutions are not found in extreme points (or nearby)



Find convex hull



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Model building

- Indicator variables
- Non-convex problems
- Nonlinear functions
- Logical expressions
- Transformation of “human text” to ILP

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Indicator variables

- Most important modelling tool!
- $\delta \in \{0, 1\}$
- $\delta = 1$ if and only if some event happens.

Model:

$$\delta = 1 \Leftrightarrow x > 0$$

$$\delta \in \{0, 1\}, x \geq 0$$

$$\delta = 1 \Rightarrow x > 0$$

$\delta = 1 \Rightarrow x \geq \varepsilon$ ε level for x regarded as 0
 $x - \varepsilon\delta \geq 0, \delta \in \{0, 1\}$

$$x > 0 \Rightarrow \delta = 1$$

$\delta = 0 \Rightarrow x = 0$
 $x - M\delta \leq 0, \delta \in \{0, 1\}$ M upper bound on x

Indicator variables

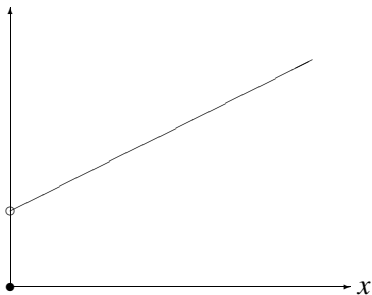
Logical implications $X \Leftrightarrow Y$

X	Y	$X \Rightarrow Y$	$X \Leftrightarrow Y$	$\neg X \Rightarrow \neg Y$
T	T	T	T	T
T	F	F	F	T
F	T	T	F	F
F	F	T	T	T

Fixed-charge problem

cost function

$$f(x) = \begin{cases} ax + b & \text{if } x > 0 \\ 0 & \text{if } x = 0 \end{cases}$$



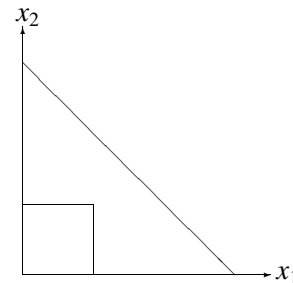
Model:

$$\begin{cases} \text{minimize} & ax + \delta b \\ \text{subject to} & x - M\delta \leq 0 \\ & x - \varepsilon\delta \geq 0 \\ & \delta \in \{0, 1\}, x \geq 0 \end{cases}$$

Non-convex problems

constraints:

$$\begin{aligned} x_1 + x_2 &\leq b \\ x_1 \geq 1 \text{ or } x_2 &\geq 1 \\ x_1, x_2 &\geq 0 \end{aligned}$$



Modeling tool

$$\delta = 1 \Rightarrow x \geq \varepsilon$$

Two indicator variables δ_1, δ_2 :

$$\begin{cases} x_1 + x_2 &\leq b \\ \delta_1 + \delta_2 &\geq 1 \\ x_1 - 1\delta_1 &\geq 0 \\ x_2 - 1\delta_2 &\geq 0 \\ x_1, x_2 &\geq 0, \\ \delta_1, \delta_2 &\in \{0, 1\} \end{cases}$$

Indicator variables

“if A is included in the blend then B is included in the blend”

can be modeled by using constraints

$x_A > 0 \Rightarrow \delta = 1$	$x_A - M\delta \leq 0, \delta \in \{0, 1\}$ M upper bound on x_A
$\delta = 1 \Rightarrow x_B > 0$	$x_B - \epsilon\delta \geq 0, \delta \in \{0, 1\}$ ϵ level for x_B regarded as 0

Example

Assume that x_A and x_B are proportions in blend i.e. $x_A + x_B = 1$.

$$M = 1 \quad \epsilon = 0.01$$

Formulation:

$$\begin{cases} x_A - \delta & \leq 0 \\ x_B - 0.01\delta & \geq 0 \\ \delta & \in \{0, 1\} \end{cases}$$

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Indicator variables for linear inequalities

Example

“If resources needed for production of x_1, x_2 and x_3 are below the limit of one truck, then use the other truck for some other purpose.”

General form

$$\sum_{j=1}^n a_j x_j \leq b \Leftrightarrow \delta = 1, \delta \in \{0, 1\}$$

- $\sum_{j=1}^n a_j x_j \leq b \Leftrightarrow \delta = 1$ has the MIP formulation

$$\sum_{j=1}^n a_j x_j + M\delta \leq M + b$$

where M is upper bound on $\sum_{j=1}^n a_j x_j - b$

$$\delta = 1: \sum_{j=1}^n a_j x_j \leq b$$

$$\delta = 0: \sum_{j=1}^n a_j x_j - b \leq M$$

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Indicator variables for linear inequalities

- $\sum_{j=1}^n a_j x_j \leq b \Rightarrow \delta = 1$ has the MIP formulation

$$\sum_{j=1}^n a_j x_j - (m - \epsilon)\delta \geq b + \epsilon$$

where m is lower bound on $\sum_{j=1}^n a_j x_j - b$.

$$\delta = 0 \Rightarrow \sum_{j=1}^n a_j x_j \geq b + \epsilon$$

$$\delta = 0: \sum_{j=1}^n a_j x_j \geq b + \epsilon$$

$$\delta = 1: \begin{cases} \sum_{j=1}^n a_j x_j - m + \epsilon \geq b + \epsilon \\ \sum_{j=1}^n a_j x_j - b \geq m \end{cases}$$

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Indicator variables for inequalities, example

Logical condition

$$\begin{aligned} 2x_1 + 3x_2 \leq 1 &\Leftrightarrow \delta = 1 \\ \delta &\in \{0, 1\} \\ 0 \leq x_1 \leq 1, 0 \leq x_2 \leq 1 \end{aligned}$$

We find

$$\begin{aligned} M &= \text{u.b.}(\sum_{j=1}^n a_j x_j - b) \\ &= \text{u.b.}(2x_1 + 3x_2 - 1) = 4 \end{aligned}$$

and

$$\begin{aligned} m &= \text{l.b.}(\sum_{j=1}^n a_j x_j - b) \\ &= \text{l.b.}(2x_1 + 3x_2 - 1) = -1 \end{aligned}$$

choose $\epsilon = 0.01$, i.e. constraint broken when $2x_1 + 3x_2 \geq 1.01$

Constraints

$$\begin{aligned} 2x_1 + 3x_2 + 4\delta &\leq 4 + 1 \\ 2x_1 + 3x_2 - (-1 - 0.01)\delta &\geq 1 + 0.01 \end{aligned}$$

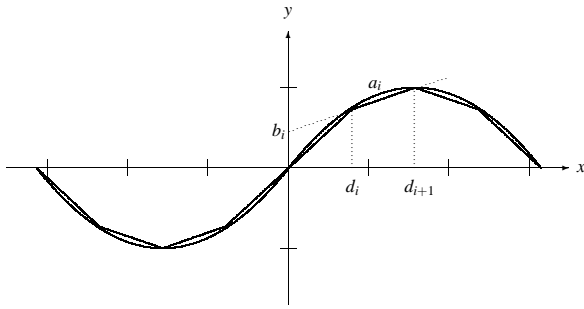
Which results in model:

$$\begin{cases} 2x_1 + 3x_2 + 4\delta \leq 5 \\ 2x_1 + 3x_2 + 1.01\delta \geq 1.01 \\ \delta \in \{0, 1\} \\ 0 \leq x_1 \leq 1, \\ 0 \leq x_2 \leq 1 \end{cases}$$

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Nonlinear functions

Frequently, the objective function or some of the constraints may contain nonlinear functions.



Approx. nonlinear function by piecewise linear function

- Split into m intervals
- For each interval $[d_i, d_{i+1}]$

$$d_i \leq x \leq d_{i+1} \Leftrightarrow y = a_i x + b_i$$

- Model as

$$\begin{cases} d_i \leq x & \Leftrightarrow \delta_1 = 1 \\ x \leq d_{i+1} & \Leftrightarrow \delta_2 = 1 \\ \delta_1 + \delta_2 = 2 & \Leftrightarrow \delta = 1 \\ y = a_i x + b_i & \Leftrightarrow \delta = 1 \end{cases}$$

- Many intervals m , better precision but much harder to solve!

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Logical conditions and 0-1 variables

- If no depot is sited here then it will not be possible to supply any of the customers from the depot.
- If we manufacture product A then we must also manufacture product B or at least one of products C and D.
- If we do not place an electronic module in this position, then no wires can be connected into this position.

Introduce an indicator variable $\delta_i \in \{0, 1\}$ with each condition X_i

$$\boxed{\text{condition } X_i \text{ is true} \Leftrightarrow \delta_i = 1}$$

In this way we may formulate:

$X_1 \vee X_2$	$\delta_1 + \delta_2 \geq 1$
$X_1 \wedge X_2$	$\delta_1 = 1, \delta_2 = 1$
$X_1 \Rightarrow X_2$	$\delta_1 - \delta_2 \leq 0$
$X_1 \Leftrightarrow X_2$	$\delta_1 - \delta_2 = 0$

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Transformation to linear form

Write up the text in ordinary mathematical form

$$(\sin(x_1) \leq \frac{1}{2} \vee x_1 x_2 \leq x_3) \Rightarrow (x_3 = 1 \vee x_2 + x_1 \leq 1)$$

Stepwise transformation

- Arithmetic functions are replaced by piecewise linear approximations of the functions.
- Products of decision variables are transformed into products of binary variables. Products of binary variables may easily be expressed as logical constraints, and thus put on binary form.
- Relations are transformed into linear inequalities with boolean variables.

$$(ax \leq b) \Leftrightarrow (\delta = 1)$$

- Boolean logics are transformed into linear form.

$$(B_1 \vee B_2) \Leftrightarrow (\delta' = 1)$$

- The resulting expression should be true $\delta_{all} = 1$

- Domains of variables are defined.

$$\delta_i \in \{0, 1\}$$

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Transformation of general constraints to linear form

Step 3:

Relation	ILP-constraints
$Ax \leq b$	$Ax + (\delta - 1)M \leq b, \quad Ax + \delta M \geq b + \epsilon$
$Ax < b$	$Ax + (\delta - 1)M \leq b - \epsilon, \quad Ax + \delta M \geq b$
$Ax > b$	$Ax + (1 - \delta)M \geq b + \epsilon, \quad Ax - \delta M \leq b$
$Ax \geq b$	$Ax + (1 - \delta)M \geq b, \quad Ax - \delta M \leq b - \epsilon$
$Ax = b$	$Ax \geq b \wedge Ax \leq b,$

Step 4:

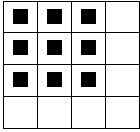
Relation	Meaning	ILP-constraints
$B_1 \vee B_2$	$\delta = 1 \Leftrightarrow \delta_1 = 1 \vee \delta_2 = 1$	$\delta - \delta_1 - \delta_2 \leq 0, \quad \delta_1 + \delta_2 - 2\delta \leq 0$
$B_1 \wedge B_2$	$\delta = 1 \Leftrightarrow \delta_1 = 1 \wedge \delta_2 = 1$	$2\delta - \delta_1 - \delta_2 \leq 0, \quad \delta_1 + \delta_2 - \delta \leq 1$
$B_1 \Rightarrow B_2$	$\delta = 1 \Leftrightarrow (\delta_1 = 1 \Rightarrow \delta_2 = 1)$	$\delta_1 - \delta_2 + \delta \leq 1, \quad \delta_1 - \delta_2 + 2\delta \geq 1$
$B_1 \Leftrightarrow B_2$	$\delta = 1 \Leftrightarrow (\delta_1 = 1 \Leftrightarrow \delta_2 = 1)$	use: $(B_1 \Rightarrow B_2) \wedge (B_2 \Rightarrow B_1)$
$\neg B_1$	$\delta = 1 \Leftrightarrow \neg(\delta_1 = 1)$	$\delta = 1 - \delta_1$

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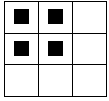
Opencast mining

The optimal solution

- Level 1 (surface)



- Level 2 (25 ft depth)



- Level 3 (50 ft depth)



- Level 4 (75 ft depth)



Net profit is 17.500 pounds.

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Ladies or tigers (Smullyan 1982)

Prisoner in castle, meets nine doors:

- Lady (immediately marry her)
- Tiger (immediately eaten)

Prefers to marry lady than be eaten

Statements on the nine doors are:

Door 1: The lady is in an odd-numbered room

Door 2: This room is empty

Door 3: Either sign 5 is right or sign 7 is wrong

Door 4: Sign 1 is wrong

Door 5: Either sign 2 or sign 4 is right

Door 6: Sign 3 is wrong

Door 7: The lady is not in room 1

Door 8: This room contains a tiger and room 9 is empty

Door 9: This room contains a tiger and sign 6 is wrong

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Ladies or tigers (Smullyan 1982)

In addition

- Only one lady
- Each other room: Tiger or empty
- Sign on door of lady is true
- Sign on door of every tiger is false
- Sign on door of empty room can be either true or false.

No unique solution until the prisoner is told whether or not room eight is empty. Then unique solution

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Ladies or tigers (Smullyan 1982)

Define subscripts $i = 1, \dots, 9$ and $j = 1, \dots, 3$ where (1 lady, 2 tiger, 3 empty) and as above variables are

$$x_{i,j} = \begin{cases} 1 & \text{if door } i \text{ hides prize } j \\ 0 & \text{otherwise} \end{cases}$$

$$t_i = \begin{cases} 1 & \text{if statement on door } i \text{ is true} \\ 0 & \text{otherwise} \end{cases}$$

“Either-or” means “ordinary or”

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