

### Wednesday, December 10

Program of the day:

- "konkurrence P2"
- "spørgetime, pensum"
- Dantzig-Wolfe reformulation of an IP
- Master problem
- Subproblem
- Linear Programming – canonical form, reduced costs, etc. (Taha chapter 7)
- Example: Cutting stock problem

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### Dantzig-Wolfe Decomposition

Motivation

- If you have a large or difficult problem: split it up into smaller pieces

Applications

- Facility location problems
- Cutting Stock problems
- Air-crew Scheduling
- Vehicle Routing Problems
- ...

Two currently most promising directions for MIP:

- Branch-and-price
- Branch-and-cut

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### Dantzig-Wolfe Decomposition

The problem is split into a master problem and a subproblem

- Tighter bounds
- Better control of subproblem
- Model may become (very) large

### Delayed column generation

Write up the decomposed model gradually as needed


- Generate a few solutions to the subproblems
- Solve the master problem to LP-optimality
- Use the dual information to find most promising solutions to the subproblem
- Extend the master problem with the new subproblem solutions.


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### Motivation: Cutting stock problem

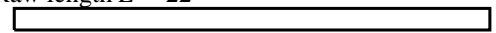
- Infinite number of raw stocks, having length  $L$ .
- Cut  $m$  piece types  $i$ , each having width  $w_i$  and demand  $b_i$ .
- Satisfy demands using least possible raw stocks.

Example:

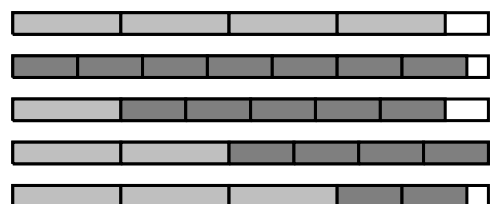
•  $w_1 = 5, b_1 = 7$  

•  $w_2 = 3, b_2 = 3$  

• Raw length  $L = 22$



Some possible cuts



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### Dantzig-Wolfe decomposition

Substituting  $X^k$  in original model getting *Master Problem*

$$\begin{aligned} \max \quad & c^1 \left( \sum_{t \in T_1} \lambda_{1,t} x^{1,t} \right) + c^2 \left( \sum_{t \in T_2} \lambda_{2,t} x^{2,t} \right) + \dots + c^K \left( \sum_{t \in T_K} \lambda_{K,t} x^{K,t} \right) \\ \text{s.t.} \quad & A^1 \left( \sum_{t \in T_1} \lambda_{1,t} x^{1,t} \right) + A^2 \left( \sum_{t \in T_2} \lambda_{2,t} x^{2,t} \right) + \dots + A^K \left( \sum_{t \in T_K} \lambda_{K,t} x^{K,t} \right) = b \\ & \sum_{t \in T_k} \lambda_{k,t} = 1 \quad k = 1, \dots, K \\ & \lambda_{k,t} \in \{0, 1\}, \quad t \in T_k \quad k = 1, \dots, K \end{aligned}$$

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### Strength of linear master model

Solving LP-relaxation of master problem, is equivalent to (Wolsey Prop 11.1)

$$\begin{aligned} \max \quad & c^1 x^1 + c^2 x^2 + \dots + c^K x^K \\ \text{s.t.} \quad & A^1 x^1 + A^2 x^2 + \dots + A^K x^K = b \\ & x^1 \in \text{conv}(X^1) \quad x^2 \in \text{conv}(X^2) \quad \dots \quad x^K \in \text{conv}(X^K) \end{aligned}$$

**Proof:** Consider LP-relaxation

$$\begin{aligned} \max \quad & c^1 \left( \sum_{t \in T_1} \lambda_{1,t} x^{1,t} \right) + c^2 \left( \sum_{t \in T_2} \lambda_{2,t} x^{2,t} \right) + \dots + c^K \left( \sum_{t \in T_K} \lambda_{K,t} x^{K,t} \right) \\ \text{s.t.} \quad & A^1 \left( \sum_{t \in T_1} \lambda_{1,t} x^{1,t} \right) + A^2 \left( \sum_{t \in T_2} \lambda_{2,t} x^{2,t} \right) + \dots + A^K \left( \sum_{t \in T_K} \lambda_{K,t} x^{K,t} \right) = b \\ & \sum_{t \in T_k} \lambda_{k,t} = 1 \quad k = 1, \dots, K \\ & \lambda_{k,t} \geq 0, \quad t \in T_k \quad k = 1, \dots, K \end{aligned}$$

Informally speaking we have

- joint constraint is solved to LP-optimality
- block constraints are solved to IP-optimality

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### Strength of Lagrangian relaxation

- $z^{LPM}$  be LP-solution value of master problem
- $z^{LD}$  be solution value of lagrangian dual problem

(Theorem 11.2)

$$z^{LPM} = z^{LD}$$

**Proof:** Lagrangian relaxing joint constraint in

$$\begin{aligned} \max \quad & c^1 x^1 + c^2 x^2 + \dots + c^K x^K \\ \text{s.t.} \quad & A^1 x^1 + A^2 x^2 + \dots + A^K x^K = b \\ & D^1 x^1 + \dots \leq d_1 \\ & \quad \quad \quad + D^2 x^2 \leq d_2 \\ & \quad \quad \quad \dots \leq \vdots \\ & \quad \quad \quad \quad \quad \quad \quad D^K x^K \leq d_K \\ & x^1 \in \mathbb{Z}_+^{n_1} \quad x^2 \in \mathbb{Z}_+^{n_2} \quad \dots \quad x^K \in \mathbb{Z}_+^{n_K} \end{aligned}$$

Using result next page

$$\begin{aligned} \max \quad & c^1 x^1 + c^2 x^2 + \dots + c^K x^K \\ \text{s.t.} \quad & A^1 x^1 + A^2 x^2 + \dots + A^K x^K = b \\ & x^1 \in \text{conv}(X^1) \quad x^2 \in \text{conv}(X^2) \quad \dots \quad x^K \in \text{conv}(X^K) \end{aligned}$$

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### Strength of Lagrangian Relaxation (section 10.2)

Integer Programming Problem

$$\begin{aligned} \text{maximize} \quad & cx \\ \text{subject to} \quad & Ax \leq b \\ & Dx \leq d \\ & x_j \in \mathbb{Z}_+, \quad j = 1, \dots, n \end{aligned}$$

Lagrange Relaxation, multipliers  $\lambda \geq 0$

$$\begin{aligned} \text{maximize} \quad & z_{LR}(\lambda) = cx - \lambda(Dx - d) \\ \text{subject to} \quad & Ax \leq b \\ & x_j \in \mathbb{Z}_+, \quad j = 1, \dots, n \end{aligned}$$

for best multiplier  $\lambda \geq 0$



$$\boxed{\max \left\{ cx : Dx \leq d, x \in \text{conv}(Ax \leq b, x \in \mathbb{Z}_+) \right\}}$$

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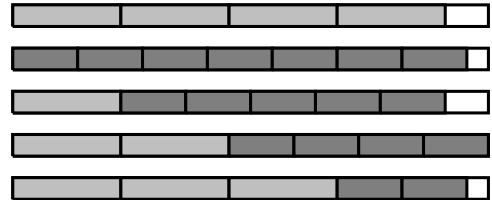
**Delayed column generation, linear master**

- Master problem can (and will) contain many columns
- To find bound, solve LP-relaxation of master
- Delayed column generation gradually writes up master

**Delayed column generation, linear master**

- $w_1 = 5, b_1 = 7$  
- $w_2 = 3, b_2 = 3$  
- Raw length  $L = 22$

Some possible cuts



In matrix form

$$A = \begin{pmatrix} 4 & 0 & 1 & 2 & 3 & \dots \\ 0 & 7 & 5 & 4 & 2 & \dots \end{pmatrix}$$

LP-problem

$$\begin{aligned} \min & \quad cx \\ \text{s.t.} & \quad Ax = b \\ & \quad x \geq 0 \end{aligned}$$

where

- $b = (7, 3)$ ,
- $x = (x_1, x_2, x_3, x_4, x_5, \dots)$
- $c = (1, 1, 1, 1, 1, \dots)$ .

**Simplex in matrix form (Taha section 7.1)**

$$\begin{aligned} \text{maximize} & \quad cx \\ \text{subject to} & \quad Ax = b \\ & \quad x \geq 0, \end{aligned}$$

Reformulation in matrix form

$$\begin{pmatrix} 1 & -c \\ 0 & A \end{pmatrix} \begin{pmatrix} z \\ x \end{pmatrix} = \begin{pmatrix} 0 \\ b \end{pmatrix}$$

Assume

- $x_B$  set of basis variables
- $c_B$  coefficients in  $c$  corresponding to basis
- $A_B$  coefficients in  $A$  corresponding to basis

Equivalent form

$$\begin{pmatrix} 1 & c_B A_B^{-1} A - c \\ 0 & A_B^{-1} A \end{pmatrix} \begin{pmatrix} z \\ x \end{pmatrix} = \begin{pmatrix} c_B A_B^{-1} b \\ A_B^{-1} b \end{pmatrix}$$

Table page 295 in Taha

basis	$x_j$	solution
$z$	$c_B A_B^{-1} A_j - c_j$	$c_B A_B^{-1} b$
$x_B$	$A_B^{-1} A_j$	$A_B^{-1} b$

**Simplex in matrix form**

Basis variables and non-basis variables

$$x_B = (x_1, x_2) \quad x_N = (x_3, x_4, x_5, \dots)$$

split matrix

$$A_B = \begin{pmatrix} 4 & 0 \\ 0 & 7 \end{pmatrix} \quad A_N = \begin{pmatrix} 1 & 2 & 3 & \dots \\ 5 & 4 & 2 & \dots \end{pmatrix}$$

reformulated problem

$$\begin{aligned} \min & \quad c_B x_B + c_N x_N \\ \text{s.t.} & \quad A_B x_B + A_N x_N = b \\ & \quad x \geq 0 \end{aligned}$$

Simplex algorithm sets  $x_N = 0$  and solves  $A_B x_B = b$  getting

$$x_B = A_B^{-1} b$$



corresponding objective function

$$z = c_B A_B^{-1} b + x_N (c_N - c_B A_B^{-1} A_N)$$

Since dual variables  $y = c_B A_B^{-1}$  we have

$$z = yb + x_N (c_N - yA_N)$$

**Delayed column generation (example)**

- $w_1 = 5, b_1 = 7$  
- $w_2 = 3, b_2 = 3$  
- Row length  $L = 22$

Initially we choose only the trivial cutting patterns

$$A = \begin{pmatrix} 4 & 0 \\ 0 & 7 \end{pmatrix}$$

Solve LP-problem

$$\begin{aligned} \min & \quad cx \\ \text{s.t.} & \quad Ax = b \\ & \quad x \geq 0 \end{aligned}$$

i.e.

$$\begin{pmatrix} 4 & 0 \\ 0 & 7 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 7 \\ 3 \end{pmatrix}$$

with solution  $x_1 = \frac{7}{4}$  and  $x_2 = \frac{3}{7}$ .

The dual variables are  $y = c_B A_B^{-1}$  i.e.

$$(1 \ 1) \begin{pmatrix} \frac{1}{4} & 0 \\ 0 & \frac{1}{7} \end{pmatrix} = \begin{pmatrix} \frac{1}{4} \\ \frac{1}{7} \end{pmatrix}$$

**Small example (continued)**

Find entering variable

$$\begin{aligned} A &= \begin{pmatrix} 1 & 2 & 3 & \dots \\ 5 & 4 & 2 & \dots \end{pmatrix} & \begin{matrix} \frac{1}{4} \leftarrow y_1 \\ \frac{1}{7} \leftarrow y_2 \end{matrix} \\ c_N - yA_N &= (1 - \frac{27}{28} \quad 1 - \frac{30}{28} \quad 1 - \frac{29}{28} \quad \dots) \end{aligned}$$

We could also solve optimization problem

$$\begin{aligned} \min & \quad 1 - \frac{1}{4}x_1 - \frac{1}{7}x_2 \\ \text{s.t.} & \quad 5x_1 + 3x_2 \leq 22 \\ & \quad x \geq 0, \text{ integer} \end{aligned}$$

which is equivalent to knapsack problem

$$\begin{aligned} \max & \quad \frac{1}{4}x_1 + \frac{1}{7}x_2 \\ \text{s.t.} & \quad 5x_1 + 3x_2 \leq 22 \\ & \quad x \geq 0, \text{ integer} \end{aligned}$$

This problem has optimal solution  $x_1 = 2, x_2 = 4$ .

Reduced cost of entering variable

$$1 - 2\frac{1}{4} - 4\frac{1}{7} = 1 - \frac{30}{28} = -\frac{1}{14} < 0$$

**Small example (continued)**

Add new cutting pattern to  $A$  getting

$$A = \begin{pmatrix} 4 & 0 & 3 \\ 0 & 7 & 2 \end{pmatrix}$$

Solve problem to LP-optimality, getting primal solution

$$x_1 = \frac{5}{8}, x_3 = \frac{3}{2}$$

and dual variables

$$y_1 = \frac{1}{4}, y_2 = \frac{1}{8}$$

Note, we do not need to care about “leaving variable”

To find entering variable, solve

$$\begin{aligned} \max & \quad \frac{1}{4}x_1 + \frac{1}{8}x_2 \\ \text{s.t.} & \quad 5x_1 + 3x_2 \leq 22 \\ & \quad x \geq 0, \text{ integer} \end{aligned}$$

This problem has optimal solution  $x_1 = 4, x_2 = 0$ .

Reduced cost of entering variable

$$1 - 4\frac{1}{4} - 0\frac{1}{8} = 0$$

Terminate with  $x_1 = \frac{5}{8}, x_3 = \frac{3}{2}$ , and  $z_{LP} = \frac{17}{8} = 2.125$ .

**Questions**

- Will the process terminate?

Always improving objective value. Only a finite number of basis solutions.

- Can we repeat the same pattern?

No, since the objective functions is improved. We know the best solution among existing columns. If we generate an already existing column, then we will not improve the objective.

### The Cutting Stock Problem (general model)

- Infinite number of raw stocks, having length  $L$ .
- Cut  $m$  piece types  $i$ , each having width  $w_i$  and demand  $b_i$ .
- Satisfy demands using least possible raw stocks.

IP-problem:

$$\begin{aligned} \min \quad & \sum_{j=1}^n x_j \\ \text{s.t.} \quad & \sum_{i=1}^m w_i a_{ij} \leq Lx_j & j = 1, \dots, n \\ & \sum_{j=1}^n a_{ij} \geq b_i, & i = 1, \dots, m \\ & a_{ij} \geq 0, \text{ integer} & i = 1, \dots, m, j = 1, \dots, n \\ & x_j \in \{0, 1\} & j = 1, \dots, n \end{aligned}$$

where

- $n$  upper bound on number of raw stocks.
- $x_j$  is 1 if raw stock  $j$  is used.
- $a_{ij}$  is number of pieces type  $i$  cut of stock  $j$ .

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### Cutting Stock: Better relaxation

- Write up all different cutting patterns
- Solve the LP-relaxation

$$\begin{aligned} \min \quad & \sum_{j=1}^n x_j \\ \text{s.t.} \quad & \sum_{i=1}^m w_i a_{ij} \leq Lx_j & j = 1, \dots, n \\ & \sum_{j=1}^n a_{ij} x_j \geq b_i, & i = 1, \dots, m \\ & a_{ij} \geq 0, \text{ integer} & i = 1, \dots, m, j = 1, \dots, n \\ & x_j \in \{0, 1\} & j = 1, \dots, n \end{aligned}$$

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### Cutting Stock: Delayed column generation

Choosing variable to enter basis

$$z = yb + x_N(c_N - yA_N)$$

where  $y = c_B A_B^{-1}$ .

For every column  $a_j$  in  $A$ , the coefficient of variable  $x_j$  is

$$1 - \sum_{i=1}^m y_i a_{ij}$$

Thus to find the most negative coefficient we solve

$$\begin{aligned} z^S = \min \quad & 1 - \sum_{i=1}^m y_i x_i \\ \text{s.t.} \quad & \sum_{i=1}^m w_i x_i \leq L \\ & x \geq 0, \text{ integer} \end{aligned}$$

Delayed column generation

- Columns in  $A$  are generated on the fly
- The process is greedy
- Terminate when no variable can enter basis ( $z^S \geq 0$ )
- Hopefully a small set of columns need to be generated

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